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An Analysis Of The Development And Application Of Orthogonal Polynomials With An Emphasis On The Legendre Polynomials

Francis Radnoti Southern Adventist University April 19, 2002

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I. Introduction:

The purpose of this paper is to first and foremost explain the concept of orthogonal polynomials to the student who has no significant background in numerical analysis or theoretical physics. Commencing with the common problem of finding a polynomial approximation to a given function on a closed interval, I will endeavor to show a construction of concepts and theorems from calculus, linear algebra, and real analysis which develops the importance of orthogonal polynomials. After proving a popular method for constructing a family of orthogonal polynomials, we will then use the method to derive one of the most basic families, the Legendre polynomials. We will then take a look at the first few Legendre polynomials and examine recurrence relations for generating new ones.

This family has many interesting applications in different fields of mathematics and physics. The most common of these is the role they play in the least square approximation problem on the interval (-1,1). In fact, the set of Legendre polynomials up to degree n ultimately provides the best least square approximation to a function f(x) on (-1,1).

The influence of Legendre polynomials also extends to Gaussian quadrature nodes, differential equations, and spherical harmonics, among other topics. And when expanding our outlook to all families of orthogonal polynomials, the topics are almost endless. Consequently, the field of orthogonal polynomials is useful in a variety of ways, and quite valuable to mathematicians, statisticians, and physicists alike.

¹ Hildebrand 274

II. Least Squares Approximation Problem and Linear Independence

When we speak of least squares approximation, we want to find, for a given a function f in C[a,b], a polynomial of degree at most n that will minimize the expression $\int [f(x) - P_n(x)]^2 dx$ across the interval [a,b].

See Section (1)

As you can see, for each P_n , this method requires us to solve an (n+1) by (n+1) matrix. Unfortunately, solving this matrix for P_n does not lessen the amount of work needed to solve for P_{n+1} . We will now look at the orthogonal polynomials approach to this problem. First we will need a few definitions and theorems regarding linear independence.

See Section (2)

III. Orthogonal Sets of Functions

Here, we will look at some definitions and theorems that show the properties of orthogonal polynomials. The first definition is that of a weight function, which is very important as it is one of the main characteristics that distinguishes between families of orthogonal polynomials. For instance, the Legendre polynomials that we will be dealing with have the simple weight function $w(x) \equiv 1$ on [-1, 1]. However, the Jacobi, Chebyshev, and Gegenbauer polynomials have more complicated weight functions, usually in the form of $(1 - x^2)^k$ for some predetermined k. The Hermite and Laguerre polynomials have exponential weight functions.³

See Section (3)

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² Burden 451

Before we move on to the construction of orthogonal sets of functions, we need to show some basic properties of even and odd functions that will simplify our work later.

Thm 3: If f and g are even functions, then fg is even.

Proof: Suppose f and g are even functions.

Then fg(-x) = f(-x)g(-x) = f(x)g(x) = fg(x). Thus fg is even.

Thm 4: If f and g are odd functions, then fg is even.

<u>Proof</u>: Suppose f and g are odd functions.

Then fg(-x) = f(-x)g(-x) = (-f(x))(-g(x)) = fg(x). Thus fg is even.

Thm 5: If f is an odd function and g is an even function, then fg is odd.

<u>Proof</u>: Suppose f is odd and g is even.

Then fg(-x) = f(-x)g(-x) = (-f(x))g(x) = -f(x)g(x) = -fg(x). Thus fg is odd.

Also, for future reference, we need to discuss the outcome of even and odd integrals over symmetric intervals. Since the Legendre polynomials are defined on the symmetric interval [-1,1], it is evident that this will come in handy later.

See Section (4)

Now, the following theorem, based on the Gram-Schmidt process⁴, describes how to construct orthogonal polynomials on a closed interval [a, b] with respect to a given weight function w. After describing the construction process, we will use the principle

⁴ Solow 354

of mathematical induction to show that the set of polynomials generated are indeed orthogonal. After that we will apply certain conditions to the process to generate a set of orthogonal polynomials known as the Legendre polynomials.

See Section (5)

IV. Applications of Legendre Polynomials

Legendre polynomials are used in Gaussian quadrature, or more specifically, the roots of Legendre polynomials are used as nodes in Gaussian quadrature. To explain, methods of quadrature are aimed at finding more efficient and accurate ways to approximate integrals. For instance, any calculus student is familiar with some of the more basic quadrature methods, such as the mid-point method, Simpson's rule, and Trapezoidal rule. All of these yield approximations to $\int f(x)$ over a given interval [a,b].

These methods become a bit more complicated when the idea of adaptive quadrature is introduced. An efficient technique of adaptive quadrature can distinguish the amount of functional variance and adapt the step size to the varying requirements of a problem. For instance, the nodes get closer together as the function variance starts getting more extreme. As such a method, Gaussian quadrature chooses the points for evaluation in an optimal, rather than equally spaced, manner. More specifically, the nodes $x_1, x_2, ... x_n$ that are needed to produce an integral approximation formula to give exact results for any polynomial of degree less than 2n on the interval (-1,1), are in fact the roots of the nth-degree Legendre polynomial.

Beckmann shows that the Legendre polynomials have an important use in differential equations as well. It turns out that as a direct result from the weight and

•

⁵ Burden 207

boundary conditions of the Legendre polynomials, they are the solution to the differential equation: $(1-x^2)d^2y/dx^2 - 2x dy/dx + n(n+1)y = 0.6$

The Legendre polynomials are primarily met in the solution of partial differential equations in spherical coordinates.⁷ They are also encountered in probability theory, where they are associated with the uniform distribution.

While the uses for the Legendre polynomials are well documented, it is important to realize that there are many other families of orthogonal polynomials, each with their own important uses. For instance, the Chebyshev polynomials are used to generate an algorithm for the efficient calculation of hypergeometric probabilities. Jacobi polynomials are used to evaluate the weights belonging to a class of quadrature rules. And in general, various families of orthogonal polynomials can be used for the analysis of a trend.

The importance of orthogonal polynomials is not merely a thing of the past either. The Rayleigh-Ritz method, first proposed in 1985, uses boundary characteristic orthogonal polynomials to more efficiently analyze the vibration of certain structures.

More than one hundred papers that used this method have been reported and discussed over the past twelve years. 11

⁶ Beckmann 46

⁷ Beckmann 75

⁸ Alvo 1

Smith 128

¹⁰ Berry 139

¹¹ Chakraverty 1

In conclusion, the field of orthogonal polynomials does not appear to be that comprehensive at first. However, the areas of application are so widespread in subject matter and difficulty that one could devote a lifetime to studying them.

[1] Let Pa(x) = anx" + an x" + --- + a1x + a0 = Zakx We want to find coefficients ao, a, --, an that will insnimize E = 5 (fex - \(\S a_x \times \) dx. Picture We can view E as a function of ap, a, an where to minimize E, we need $\frac{\partial E}{\partial a} = \frac{\partial E}{\partial a} = \frac{1}{2a}$ F= [(FUX) - 2 fux) \ \ a_k x + [\ \ a_k x k]^2 dx = [f(x)] dx - 2 \(\int a_x \) f(x) \(\int dx + \) [\(\int a_x \) \ dx So for each j=0,1, --, n $\frac{\partial E}{\partial a_i} = -2 \int_a^b f(x) \cdot x^j dx + 2 \sum_{k=0}^{\infty} a_k \int_a^b x^{j+k} dx$

To find Pn(x), the (n+1) linear normal equations \(\sum_{a_k}\int \text{x}^{\frac{1}{2}k} \, \dx = \int \frac{5}{2}(x) \cdot \text{x}^2 \, \dx , \quad j=0,1,...,n be solved for each of the (n+1) Unknowns a; (END SECTION [17) Def 1: The set of functions { \$\phi_0, \phi_1, \dots, \phi_3} is linearly independent on [a,b] if whenever Cod(x) + Cod(x) + cod(x) = 0 For all x = [a, 6] Co = C, = --- = Cn = 0. Thm1: Suppose for each j=0,1, --, n, D; is a polynomial of degree j. Then E.P., P., Das linearly independent on any interval a, b] real numbers Proof: Suppose Co, C, --- Ch are for which PCX = codo(x) + Gd,(x) + --- + Cndn(x) = 0 for all x6 [a, b]. Since P(x) = 0 on [a,b] the coefficient of xn is zero, (because

	showing that the set Epo, p,, p, 3	
	spans The Since the set is linearly	
	independent, and since IIn has	a.
	dimension n+1, Eqo, P,, p, forms	
	a basis for Th. Thus, by the definition	
-	of basis, any polynomial in TIn can	
7	be written as a linear combination	ретаропо ник осторизация.
	OF \$0,\$1,, \$\dagger\$_\(\pi\) (END SECTION [2])	
		Apr ilancial Surface
)-		
		Stead of the state

-	Def 3:	
73]	An integrable function w is called a	
-	weight function on the interval I if	
	for all x ∈ I, wex> > o, and vex cannot	-
	be the zero function on any subinterval	Aprillada a Paris
3	of I, (including I itself).	_
-	Def 4: Epo, p,, p, 3 is an orthogonal	- who is a substitute of the s
()	set of functions on [a, b] with respect	
	to the weight function w if:	
	$\int_{a}^{b} w(x) \cdot \theta_{j}(x) \cdot \theta_{k}(x) dx = \begin{cases} 0 & \text{whenever } j \neq k \\ \alpha_{k} \neq 0 & \text{whenever } j = k \end{cases}$	
	Also, if $\alpha_{k}=1$ for each $k=0,1,,n$	-
	the set is orthonormal. (END SECTION [3])	
		ing primaripana
)-)-		
-		

47 Thm 6: If f is an integrable, odd function defined on the interval [-a,a] for some a 70, then I fax dx = 0. Proof: Sfundx = Sfundx + Sfundx = J-fundx + fordx = fr-x)dx + fr(x)dx = - fafexidx + fafexidx = O.M. IF I is an integrable, even function defined on the interval [-a,a] for some a >0, then I fix) dx = 2) fix) dx. Proof: I fixedx = I fixedx + I fundx = - J Fix dx + J fundx = - 5 f(-x) dx + 5 fix) dx = 5 fex dx + fa fex dx = 2 5 FUX) . dx . M. (BND SECTION [4]) 5] Thm 8: The set of polynomials defined in the following way is orthogonal on [a, b] with respect to the weight function w.1 $\phi_0(x) \equiv 1$, $\phi_1(x) = x - B$, for each x in [a, b]where B = J x. ww [\$ (x)] dx J WCX) - [\$ (X)] dx. and when K=2, $\phi_{k}(x) = (x-B_{k})\phi_{k-1}(x) - C_{k}\phi_{k-2}(x)$ For each X in [a, b] where $B_{k} = \int_{a}^{b} x \cdot \omega(x) \cdot \left[\phi_{k-1}(x) \right] dx \quad \text{and} \quad C_{k} = \int_{a}^{b} x \cdot \omega(x) \, \phi_{k-1}(x) \, \phi_{k-2}(x) \cdot dx$ [WON) [Q -2 (X)] dx Proof: First, we will show that {\$\phi_0, \phi_1 \} is orthogonal on [a, b] with respect to W. Based on the definition of orthogonality. we need to show three things: (1) JUXI [do(x)] dx = do for some d. > 0.

	(2) Swar. [ø, (x)] dx = a, for some d, 70.	-
	(3) $\int_{0}^{\infty} \omega(x) \cdot \phi_{0}(x) \cdot \phi_{1}(x) dx = 0$.	_
	For (1) it follows from the definition of weight	
	function that $\int_{a}^{b} \omega(x) \left[\phi(x) \right]^{2} dx = \int_{a}^{b} \omega(x) dx > 0$.	Talan Nov
	For (2) we must recognize that	-
	Q(x)= X - \(\frac{\frac{1}{x} \cdot \omega \cdot \dx}{\int_{a}^{b} \omega \cdot \omega \dx} \) for all xe [a, b].	
)-	and thus $\phi_i(x)$ is a linear function.	
	We have that $\forall x \in [a, b] (wx) \ge 0)$. Also we	1
	have that $\forall x \in [a,b] ([a,x)]^2 \ge 0)$. Thus $\forall x \in [a,b]$	- -
	(WCX)·[d(CX)] ² ≥0). Clearly, [aux)·[a(x)] ² ≥0.	
	Now, there exists some subinterval (a,, b,) C	
	[a,b] where wex >0 for all x e (a,b).	
	And on [a, b], [0,(x)] can have a maximum	
)-	of one zero (because it has degree 2 and never crosses	
	the x-axis). So if [dix] has no zeroes	***************************************
		1

on (a, b,), then I wex)[dex)]dx > 0 -> [wxx) [q, w] dx > 0. If it has one zero (a,b,) let us call it x, Then [wxx). [q, cx)] dx >0 -> J'WX).[\$ (X)]2dx >0. (3) is fairly straightforward: $\int_{a}^{b} w(x) \cdot \phi(x) \cdot \phi(x) \cdot dx = \int_{a}^{b} w(x) \cdot \left[x - \int_{a}^{b} x w(x) dx \right] dx$ Seeks of the State [[[wxxx - wxx)] x:wxxxdx] dx J'ww.dx $= \int_{a}^{b} \omega(x) \cdot x \cdot dx - \int_{a}^{b} \left[\frac{\omega(x) \cdot \int_{a}^{b} x \cdot \omega(x) \cdot dx}{\int_{a}^{b} \omega(x) \cdot dx} \right] dx$ = fbwwxxdx - fbxwwdx. fbwwrdx 5 wardx Pulm X dx - Pulm X dx = 0. Now continuing with the process of induction, we need to show that if

Edo, d, --, on 3 is a set of orthogonal polynomials constructed in this manner then {\$\phi_0, \Phi_1, ---, \Phi_n \} is as well Suppose { Po, Pi, ..., Pn} is a set of orthogonal polynomials on [a, b]. We need to show that for each K=0,1,--, n, Jwxx.gxx.gxx.dx=0 Now, since the recursion formula tells us that : On (x) = (x-Bn) On (x) - Cny On-1(x), we can sub this value into the integral and expand to get: Juan. x. & con of condx - Bmy www. & con of condx -[cn+1] was duck of not each k=0s 1s --- n Now, think of this equation in the form as shown above. look at X = Swxx.x.pxxx.pnxx.dx each K= O,1, ---, n. We will show in

the upcoming corollary that X=0 when k=0,1,, n-2. For now, we will make this claim. Now Y=3, Jwayqxxyqnxydx for each k=0,1,, n. Therefore, Y= Jxwax[qnxx]^2dx. Jwayqxxydx = 0 when k=0,1,, n-1 and = Jxwax[qnxx]^2dx when k=n Z=cn, Jwaxqxxydxyqnxxydx for each k=0,1,, n. = Jxwaxqxxyqnxydxyqnxxydx. Jwaxqxxyqnxydx Jawxx[qnxx]^2dx = 0 when k=0,1,, n-2, and = Jxwaxqxxyqnxydx. Jwaxqxxydxxydx = 0 when k=0,1,, n-2, and = Jxwaxqxxyqxxydxxydxxydxxydxxydxxydxxydxxydxx	* B		
Hhis claim. Now $Y = B_{n+1} \int_{a}^{b} u(x) \phi_{k}(x) \phi_{n}(x) dx$ for each $k = 0, 1,, n$. Therefore, $Y = \int_{a}^{b} x \cdot w(x) [\phi_{n}(x)]^{2} dx$. $\int_{a}^{b} u(x) [\phi_{n}(x)]^{2} dx$ $= 0 \text{when } k = 0, 1,, n-1 \text{and}$ $= \int_{a}^{b} x \cdot w(x) [\phi_{n}(x)]^{2} dx \text{when } k = n$ $Z = c_{n+1} \int_{a}^{b} w(x) \phi_{k}(x) \phi_{n+1}(x) dx \text{for each } k = 0, 1,, n$ $= \int_{a}^{b} x \cdot w(x) \phi_{k}(x) \phi_{n+1}(x) dx \cdot \int_{a}^{b} w(x) \phi_{k}(x) \phi_{n+1}(x) dx$ $\int_{a}^{b} w(x) [\phi_{n+1}(x)]^{2} dx$ $= 0 \text{when } k = 0, 1,, n-2, \text{and}$ $= \int_{a}^{b} x \cdot w(x) \phi_{k}(x) \phi_{n+1}(x) dx \text{when } k = n-1, \text{and}$ $= \int_{a}^{b} x \cdot w(x) \phi_{k}(x) \phi_{n+1}(x) dx \text{when } k = n-1, \text{and}$ $= 0 \text{when } k = n.$ Now, returning our attention to the	the upcom	ing corollary. That X=0 when	
Each k=0,1,, n. Therefore, I= \[\int x \comp \left[\sigma\comp \right]^2 \dx \cdot \comp \left[\sigma\comp \right]^2 \dx \] \[\int \int \comp \left[\sigma\comp \right]^2 \dx \cdot	K=0,1,-	-, n-2. For now, we will make	
$\int_{a}^{b} x \cdot \omega(x) \left[\varphi_{n}(x) \right]^{2} dx \cdot \int_{a}^{b} \omega(x) \varphi_{n}(x) \cdot \varphi_{n}(x) dx$ $= 0 \text{ when } k = 0, 1,, n-1 \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \left[\varphi_{n}(x) \right]^{2} dx \text{ when } k = n$ $Z = c_{n+1} \int_{a}^{b} \omega(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) dx \text{ for each } k = 0, 1,, n$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) dx \cdot \int_{a}^{b} \omega(x) \cdot \varphi_{n}(x) dx$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) dx \cdot \int_{a}^{b} \omega(x) \cdot \varphi_{n}(x) dx$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}$	this d	aim. Now I= Bn, Jux) ph(x) ph(x) ph(x) dx for	
$\int_{a}^{b} \omega(x) \left[\varphi_{n}(x) \right]^{2} dx$ $= 0 \text{ when } k = 0, 1,, n-1 \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \left[\varphi_{n}(x) \right]^{2} dx \text{ when } k = n.$ $Z = c_{n+1} \int_{a}^{b} \omega(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) dx \text{ for each } k = 0, 1,, n.$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \varphi_{n}(x) \cdot \varphi_{n}(x) dx \cdot \int_{a}^{b} \omega(x) dx \cdot \int_{$	each K=C	31,, n. Therefore, Y=	
= 0 when $k=0,1,,n-1$ and = $\int_{a}^{b} x \cdot \omega(x) \cdot [\mathcal{O}_{n}(x)]^{2} dx$ when $k=n$. $Z = c_{n+1} \int_{a}^{b} \omega(x) \cdot \mathcal{O}_{k}(x) \cdot \mathcal{O}_{n-1}(x) dx$ for each $k=0,1,,n$. = $\int_{a}^{b} x \cdot \omega(x) \cdot \mathcal{O}_{k}(x) \cdot \mathcal{O}_{k-1}(x) dx$ for each $k=0,1,,n$. = $\int_{a}^{b} x \cdot \omega(x) \cdot \mathcal{O}_{k}(x) \cdot \mathcal{O}_{k-1}(x) dx$ for each $k=0,1,,n-1$ and = $\int_{a}^{b} x \cdot \omega(x) \cdot \mathcal{O}_{k}(x) \cdot \mathcal{O}_{k-1}(x) dx$ when $k=n-1$, and = $\int_{a}^{b} x \cdot \omega(x) \cdot \mathcal{O}_{k}(x) \cdot \mathcal{O}_{k-1}(x) dx$ when $k=n-1$, and = 0 when $k=0$. Now, returning our attention to the	John X. Wo	N[qn(x)]2.dx. jw(x) qx(x). qn(x) dx	
$Z = c_{n+1} \int_{a}^{b} \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n}(x) \cdot dx \text{ for each } k = 0, 1,, n.$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n}(x) \cdot dx \cdot \int_{a}^{b} \omega(x) \cdot \phi_{n}(x) \cdot dx \cdot \int_{a}^{b} \omega(x) \cdot \phi_{n}(x) \cdot dx$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n}(x) \cdot dx \cdot \int_{a}^{b} \omega(x) \cdot \phi_{n}(x) \cdot dx$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n}(x) \cdot dx \text{when } k = n - 1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n}(x) \cdot dx \text{when } k = n - 1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n}(x) \cdot dx \text{when } k = n - 1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n}(x) \cdot dx \text{when } k = n - 1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n}(x) \cdot dx \text{when } k = n - 1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n}(x) \cdot dx \text{when } k = n - 1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n}(x) \cdot dx \text{when } k = n - 1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n}(x) \cdot dx \text{when } k = n - 1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n}(x) \cdot dx \text{when } k = n - 1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n}(x) \cdot dx \text{when } k = n - 1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n}(x) \cdot dx \text{when } k = n - 1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n}(x) \cdot dx \text{when } k = n - 1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n}(x) \cdot dx \text{when } k = n - 1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n}(x) \cdot dx \text{when } k = n - 1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n}(x) \cdot dx \text{when } k = n - 1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n}(x) \cdot dx \text{when } k = n - 1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n}(x) \cdot dx \text{when } k = n - 1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n}(x) \cdot dx \text{when } k = n - 1, \text{ and}$		Jawan [phun] dx	
$Z = c_{n+1} \int_{a}^{b} \omega(x) \cdot \phi_{x}(x) \cdot \phi_{x-1}(x) dx \text{ for each } k = 0,1,,n.$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{x}(x) \cdot \phi_{x-1}(x) dx \cdot \int_{a}^{b} \omega(x) \cdot \phi_{x}(x) \cdot \phi_{x}(x) \cdot \phi_{x-1}(x) dx$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{x}(x) \cdot \phi_{x-1}(x) \cdot dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{x}(x) \cdot \phi_{x-1}(x) \cdot dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{x}(x) \cdot \phi_{x-1}(x) \cdot dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{x}(x) \cdot \phi_{x-1}(x) \cdot dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{x}(x) \cdot \phi_{x-1}(x) \cdot dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{x}(x) \cdot \phi_{x-1}(x) \cdot dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{x}(x) \cdot \phi_{x-1}(x) \cdot dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{x}(x) \cdot \phi_{x-1}(x) \cdot dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{x}(x) \cdot \phi_{x-1}(x) \cdot dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{x}(x) \cdot \phi_{x-1}(x) \cdot dx \text{ when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{x}(x) \cdot \phi_{x}(x$	= 0 whe	n = 0, 1,, n-1 and	(See High High open)
$= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n-1}(x) \cdot dx \cdot \int_{a}^{b} \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n-1}(x) dx$ $= \int_{a}^{b} \omega(x) \cdot \left[\phi_{n-1}(x)\right]^{2} dx.$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n-1}(x) \cdot dx \text{when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n-1}(x) \cdot dx \text{when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n-1}(x) \cdot dx \text{when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n-1}(x) \cdot dx \text{when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n-1}(x) \cdot dx \text{when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n-1}(x) \cdot dx \text{when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n-1}(x) \cdot dx \text{when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n-1}(x) \cdot dx \text{when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n-1}(x) \cdot dx \text{when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n-1}(x) \cdot dx \text{when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n-1}(x) \cdot dx \text{when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n-1}(x) \cdot dx \text{when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n-1}(x) \cdot dx \text{when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n-1}(x) \cdot dx \text{when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n-1}(x) \cdot dx \text{when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n-1}(x) \cdot dx \text{when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n-1}(x) \cdot dx \text{when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n-1}(x) \cdot dx \text{when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n-1}(x) \cdot dx \text{when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n-1}(x) \cdot dx \text{when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n-1}(x) \cdot dx \text{when } k = n-1, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n-1}(x) \cdot dx \text{when } k = n-1, \text{ and}$	$=\int_{a}^{b} \times \cdot \omega U$	or [on(x)]? dx when k=n.	
$\int_{a}^{b} \omega(x) \cdot [\phi_{n-1}(x)]^{2} dx.$ $= 0 \text{ when } k = 0, 1,, n-2, \text{ and}$ $= \int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n}(x) \cdot \phi_{n-1}(x) \cdot dx \text{ when } k = n-1, \text{ and}$ $= 0 \text{ when } k = n.$ Now, returning our attention to the	Z = Cnrl	wext of each K=0,1,, n.	
= 0 when $k=0,1,,n-2$, and = $\int_{a}^{b} \times \cdot \omega(x) \cdot \partial_{n}(x) \cdot \partial_{n-1}(x) \cdot dx$ when $k=n-1$, and = 0 when $k=n$. Now, returning our attention to the	= \int_{A}^{b} \times \cdot \tau	ωων. φ, (x) φ, - (x) -dx · [ω(x). φ, (x) · β, - (x) dx	
= $\int_{a}^{b} x \cdot \omega(x) \cdot \phi_{n-1}(x) \cdot dx$ when $k = n - 1$, and = 0 when $k = n$. Now, returning our attention to the		$\int_{a}^{b} \omega(x) \cdot \left[\phi_{n-1}(x) \right]^{2} dx.$	_
Now, returning our attention to the	= 0 wl	k=0,1,,n-2, and	
Now, returning our attention to the	= Sax.wa	x). Ø _n (x). Ø _{n-1} (x). dx when k= n-1, and	e johan katang
	= 0 Wh	en K= n.	
Form I-I-I, we get that whenever	Now, re	turning our attention to the	
	Form X	-Y-Z, we get that whenever	

K=0,1,..., n-2, X-Y-Z=0. When K=n-1, X-Y-Z= 5 WK).x \$ _1(x). \$ (x). dx S'x.wxx. on(x). on (x). dx = 0. And when K=n, X-Y-Z = Swxxx[0,w]2dx - Jxwxx[0,w]dx = 0. :. For each k=0,1,--, n, Sww. q.(x) dx = 0 Now finally we must show that Swexs[\$\phi_{m+1} \times] dx = \alpha_{n+1} for some \alpha_{n+1} > 0. (learly, the product wix) [anxix)] > 0 for all x e [a, b]. Now, there exists some subinterval (a, b,) c [a, b] where W(X) > 0 for all X E (a, b,). And since [dm (x)] is a polynomial of degree 2(n+1), and never crosses the x-axis, has a maximum of n+1 zeroes on [a, b]. Suppose it has no zeroes on (a, b). Then Soux [pm (x)]2dx 70

which implies [wxs [anx)] dx > 0. Suppose it has at least one zero on (a, b,) Lets call the smallest one xo. Then [[(x) [(x)] dx > 0 -> [(x) [(x, (x)] dx > 0. " Ego, P, ..., Pn+13 is a set of orthogonal polynomials whenever Epo, \$1,..., \$13. : By PMI, the set {\$0,\$0,---,\$0,} generated by the method described in Thm 8, is a set of orthogonal polynomials.

Corollary 8.1 SWUX) X. Q. (X) . P. (X) . dX = 0 when K=0,1,-, N-2 Prof Let K6 801,-, n-23. By Thm 1, 88,0,-, 9km3 is linearly independent on [a, b]. Thus {\$Po, Pi, ..., Pri,} forms a basis for The Thus every polynomial of degree K+1 can be written as a linear combination of \$6,0, -, oxy Thus, for some constants Co, C7, -, CK+1 X. Q(x) = \(\subseteq Cipi(x) \). Thus \(\widetilde w(x) \subseteq (\alpha) \phi_n(x) \phi_n(x = 5 w(x). \$\phi_{\alpha}(x). (\frac{\frac{\pi}{2}}{2} ci \phi_{\alpha}(x)). dx = [W(X) · Q, (X) · Co Ø(X) · dx + + [W(X) & (X) Cx+1 Øx+1(X) · dX = Co Juw. Ow. On widx + --- + Cx+1 J ww. of (x) Ox+1(x) dx = Co(0) + C;(0) + --- + Ck;(0) From this argument, we see that 5 wext prexide = 0 where pk is any polynomial in IIn-

The set of Legendre polynomials, {Ph}, is orthogonal on [-1,1] with respect to the weight function wex = 1. The classical definition of the Legendre polynomials requires that Pn(1)= 1 for each ne I. By Using Thin 8, and disregarding the boundary condition, we will generate a constant mutiple of the Legendre polynomials. For application purposes though, this difference is just a matter of convention. (Later, we will look at the exact Legendre polynomials and the recursive relation used generate them) According to Thin 8, Po(x) = 1 on [-1,1] P,(x)= x-B,= x-) x.dx = x -0=

P2(x) = (x-B2). P,(x) - C2Po(x) $= (x - \frac{5}{1} \times \frac{3}{2} dx) \cdot x - \frac{5}{1} \times \frac{2}{2} dx = x^{2} - \frac{1}{3}$ $= \frac{5}{1} \times \frac{2}{2} dx = \frac{5}{1} \times \frac{1}{2} dx = \frac{2}{3}$ Continuing in this fashion we find that P3(x) = x3 - 3x, P4(x) = x4 - 6x2 + 35, and P₅(x) = x⁵ - 10x³ + 5x to name a few. Below is a rough sketch of P(x) through F4(x)

Thm 9: (Refinement of Thm 8 for a special case) The set of polynomials & do, d, -, on defined in the following way is orthogonal on [-a,a] (where aro) with respect to the weight function was=1: $\phi_0(x) \equiv 1$, $\phi_1(x) = x$ for each $x \in [-a, a]$ and when KZ2 (D,(x)= x.d,(x) - Cxpx-z(x) for each xe[-a,a] Where Cy = \(\times \psi_{k-1}(x) \cdot \psi_{k-2}(x) \dx $\int_{a}^{a} \left[\phi_{k-2}(x) \right]^{2} dx.$ Applying the interval and weight function to the process described in Thm8, we get that B = S x dx = 0 = 0. 5° ldx 2a Thus, p(x) = 1 and Q(x) = x for each xe[-a,a]

	Also, when $K \ge 2$, we have	-
	$B_{k} = \frac{\int_{\alpha}^{\alpha} \times \left[\mathcal{G}_{k-1}(x) \right]^{2} dx}{\int_{\alpha}^{\alpha} \left[\mathcal{G}_{k-1}(x) \right]^{2} dx}$ But $x \cdot \left[\mathcal{G}_{k-1}(x) \right]^{2} dx$	-
	(by Thm 5) and Sax [9k-1(x)] dx = 0 (by Thm 6).	
	Thus $B_k = 0$ for all $k \ge 2$. Also, when $k \ge 2$.	1 *
)	$C_{k} = \int_{a}^{a} \times \varphi_{k-1}(x) \cdot \varphi_{k-2}(x) \cdot dx = 2 \int_{a}^{a} \times \varphi_{k-1}(x) \cdot \varphi_{k-2}(x) \cdot dx$ $= \int_{a}^{a} \left[\varphi_{k-2}(x) \right]^{2} dx = 2 \int_{a}^{a} \left[\varphi_{k-2}(x) \right]^{2} \cdot dx$	
	$= \frac{\int_{0}^{q} x \cdot \phi_{k-1}(x) \cdot \phi_{k-2}(x) \cdot dx}{\int_{0}^{q} \left[\phi_{k-2}(x)\right]^{2} dx}$	
	This method saves us some work when	
	dealing with approximations on symmetric	_
	intervals.	
)-		

Hildenbrand outlines the origin of the classical definition of Legendre polynomials. Starting with the same least squares approximation problem, he searchs for a polynomial, Ør(x) (of degree r), such that Ja w(x). Or (x). gr, (x) dx = 0 where gr, is an arbitrary polynomial in TI. After integrating by parts r times, and deriving a differential equation related to \$(x), he applies the Legendre conditions (namely the ones we discussed before) to the set of Or(X) S. From the differential equation conditions, it is found that the 1th Legendre polynomial is given by Pr(x)= 1 dr (x2-1)r.

The constant term is chosen to Fit the condition that Pn(1)=1 for each net. Using this method to generate the Legendre polynomials, we get PowsI, Pick)=x, $P_2(x) = \frac{3}{2}x^2 - \frac{1}{2}$, $P_3(x) = \frac{5}{2}x^3 - \frac{3}{2}x$, and P4(x) = 35x4 - 152 + 3. as the first five Legendre polynomials. Here is a rough sketch of Po to Py on the interval [-1,1].

Additional Pn(x)'s can be determined	
from the recurrence formula:	
P(x) = 2r+1 P(x) - F(-1(x)) 1	
While the Pn(x)'s that we derived	
from Thing give very good least square	
approximations, Hildebrand concludes	Bilgs violages bione hydra
that the best possible value of Pn(x)	ender engenoone en eer
for a given nEI (to minimize E back	
in Section [1] over (-1,1)) is a linear	
combination of the Legendre polynomials	
in the form a low + a, P. (x) + + an P. (x)	
where each ar = 2r+1 5 fw. Pr(x) dx.	
(END SECTION [5])	Belgio (Algoria)
	From the recurrence formula: Prom the Prox - Frix. While the Prox s. that we derived From Thing give very good least square approximations, Hildebrand concludes that the best possible value of Prox for a given no I (to minimize E back in Section [1] over (-1,1)) is a linear combination of the Legendre polynomials in the form about + aprix + + aprix where each a = 2r+1 5 two. Prox dx.

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D. keliar a

SOUTHERN SCHOLARS SENIOR PROJECT Name: Francis Kadnoti Date: 1-18-02 Major: Mathematics SENIOR PROJECT A significant scholarly project, involving research, writing, or special performance, appropriate to the major in question, is ordinarily completed the senior year. The project is expected to be of sufficiently high quality to warrant a grade of A and to justify public presentation. Under the guidance of a faculty advisor, the Senior Project should be an original work, should use primary sources when applicable, should have a table of contents and works cited page, should give convincing evidence to support a strong thesis, and should use the methods and writing style appropriate to the discipline. The completed project, to be turned in in duplicate, must be approved by the Honors Committee in consultation with the student's supervising professor three weeks prior to graduation. Please include the advisor's name on the title page. The 2-3 hours of credit for this project is done as directed study or in a research class. Keeping in mind the above senior project description, please describe in as much detail as you can the project you will undertake. You may attach a separate sheet if you wish: Investigate the application of Orthogonal polynomials. where : project Expected date of completion 4/15/02 Signature of faculty advisor Approval to be signed by faculty advisor when completed: This project has been completed as planned: $\sqrt{e^5}$ This in an "A" project: This project is worth 3 hours of credit; Advisor's Final Signature Date Approved: Chair, Honors Committee

Dear Advisor, please write your final evaluation on the project on the reverse side of this page. Comment on the characteristics that make this "A" quality work.